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Coordination Action

ACCA

A networking view

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INTERNET FONDATION

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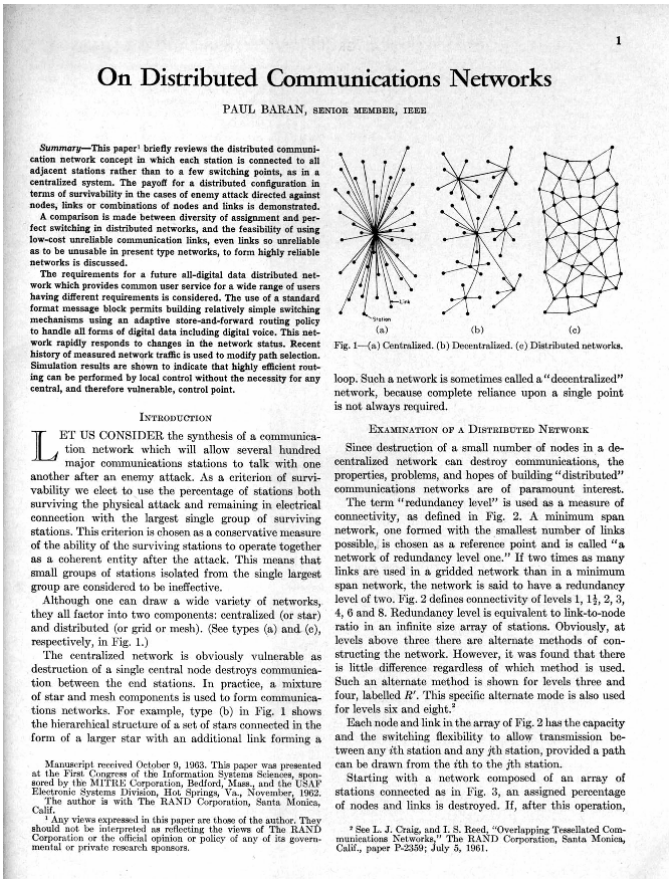

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On Distributed Communications Networks

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Summary—This paper[1] briefly reviews the distributed communication network concept in which each station is connected to all adjacent stations rather than to a few switching points, as in a centralized system. The payoff for a distributed configuration in terms of survivability in the cases of enemy attack directed against nodes, links or combinations of nodes and links is demonstrated.

A comparison is made between diversity of assignment and perfect switching in distributed networks, and the feasibility of using low-cost unreliable communication links, even links so unreliable as to be unusable in present type networks, to form highly reliable networks is discussed.

The requirements for a future all-digital data distributed network which provides common user service for a wide range of users having different requirements is considered. The use of a standard format message block permits building relatively simple switching mechanisms using an adaptive store-and-forward routing policy to handle all forms of digital data including digital voice. This network rapidly responds to changes in the network status. Recent history of measured network traffic is used to modify path selection. Simulation results are shown to indicate that highly efficient routing can be performed by local control without the necessity for any central, and therefore vulnerable, control point.

INTRODUCTION

LET US CONSIDER the synthesis of a communication network which will allow several hundred major communications stations to talk with one another after an enemy attack. As a criterion of survivability we elect to use the percentage of stations both surviving the physical attack and remaining in electrical connection with the largest single group of surviving stations. This criterion is chosen as a conservative measure of the ability of the surviving stations to operate together as a coherent entity after the attack. This means that small groups of stations isolated from the single largest group are considered to be ineffective.

Although one can draw a wide variety of networks, they all factor into two components: centralized (or star) and distributed (or grid or mesh). (See types (a) and (c), respectively, in Fig. 1.)

The centralized network is obviously vulnerable as destruction of a single central node destroys communication between the end stations. In practice, a mixture of star and mesh components is used to form communications networks. For example, type (b) in Fig. 1 shows the hierarchical structure of a set of stars connected in the form of a larger star with an additional link forming a loop. Such a network is sometimes called a "decentralized" network, because complete reliance upon a single point is not always required.

Fig. 1—(a) Centralized. (b) Decentralized. (c) Distributed networks.

EXAMINATION OF A DISTRIBUTED NETWORK

Since destruction of a small number of nodes in a decentralized network can destroy communications, the properties, problems, and hopes of building "distributed" communications networks are of paramount interest.

The term "redundancy level" is used as a measure of connectivity, as defined in Fig. 2. A minimum span network, one formed with the smallest number of links possible, is chosen as a reference point and is called "a network of redundancy level one." If two times as many links are used in a gridded network than in a minimum span network, the network is said to have a redundancy level of two. Fig. 2 defines connectivity of levels 1, 1½, 2, 3, 4, 6 and 8. Redundancy level is equivalent to link-to-node ratio in an infinite size array of stations. Obviously, at levels above three there are alternate methods of constructing the network. However, it was found that there is little difference regardless of which method is used. Such an alternate method is shown for levels three and four, labelled *R'*. This specific alternate mode is also used for levels six and eight.[2]

Each node and link in the array of Fig. 2 has the capacity and the switching flexibility to allow transmission between any *i*th station and any *j*th station, provided a path can be drawn from the *i*th to the *j*th station.

Starting with a network composed of an array of stations connected as in Fig. 3, an assigned percentage of nodes and links is destroyed. If, after this operation,

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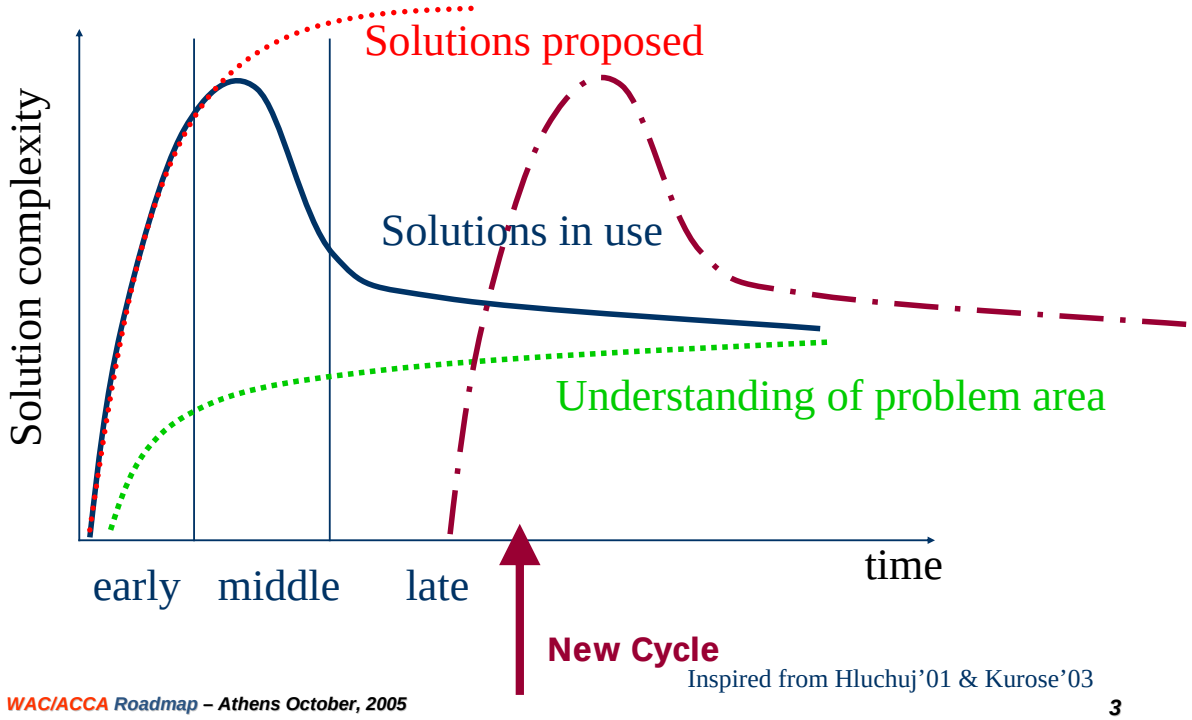
[1] Any views expressed in this paper are those of the author. They should not be interpreted as reflecting the views of The RAND Corporation or the official opinion or policy of any of its governmental or private research sponsors.

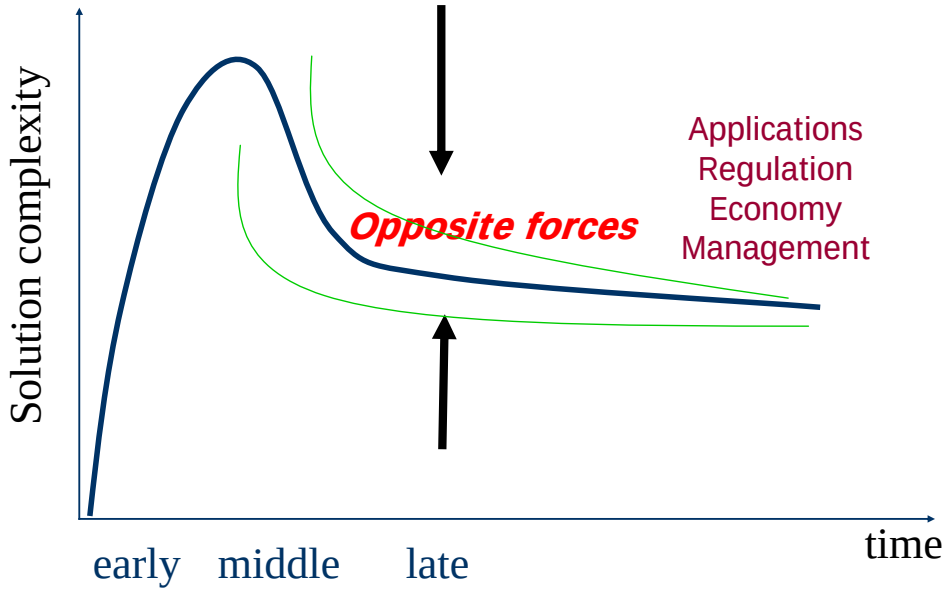
[2] See L. J. Craig, and I. S. Reed, "Overlapping Tessellated Communications Networks," The RAND Corporation, Santa Monica, Calif., paper P-2359; July 5, 1961.

The R&D « Learning » Curve



Inspired from Hluchuj'01 & Kurose'03

Autonomic Communications



Inspired from Hluchuj'01 & Kurose'03

Autonomic Communications

- Throw “Ants” at the problem!
- Networking focus
- Not a single solution
- Basic principles and architecture
- Fundamentals
- Testbeds…
- Standards …

AC Networking Issues

- The Autonomic Communication (AC) paradigm proposes a very ambitious future for communications
- Self-*
- Naming/addressing (multiple IDs) ? Autonomic entity?
- Data gathering and Knowledge Management? Interactions with envt?
- Soft-Layering (time-dependant architecture)? Internal Intercations?
- Interoperability, multiple context? Multiple (re)-actions vs artefacts?
- Behavior modeling, Composition? System Overall Evolution/Integrity?
- Service management, replication? Service adaptation?