# Μάθηση Βασισμένη σε Στιγμιότυπα (Instance-based Learning)

- Storing training examples
- No explicit model (= target function) construction
- Processing delayed until a new instance has to be classified
- Lazy learning / Memory-based learning
- Usually, instances are points in an Euclidean space
- Local approximation of real-valued or discrete-valued target functions
- Need for indexing of instances (kd-trees)
- k-nearest neighbor learning / locally weighted regression

| Sugar | Flour | Temperature | Minutes | YouLike |
|-------|-------|-------------|---------|---------|
| 3     | 5     | 250         | 120     | yes     |
| 6     | 4     | 250         | 180     | yes     |
| 5     | 4     | 200         | 120     | no      |
| 4     | 2     | 300         | 120     | yes     |
| 7     | 6     | 300         | 90      | no      |
| 8     | 3     | 200         | 90      | no      |
| 5     | 5     | 350         | 180     | yes     |
| 7     | 9     | 250         | 180     | yes     |

## A Cookie Making Example

Do you like cookies made of 5 kgs sugar and 6 kgs flour baked at 250°C for 120 minutes?

### k-nearest Neighbor Learning

- Instances described by feature vectors  $\langle a_1(x), a_2(x), \ldots, a_n(x) \rangle$ , where  $a_r(x)$  denotes the *r*th attribute of instance x
- Distance between two instances  $x_i$  and  $x_j$

$$d(x_i, x_j) = \sqrt{\sum_{r=1}^n (a_r(x_i) - a_r(x_j))^2}$$

• Approximation of discrete-valued target functions

$$f: \mathfrak{R}^n \longrightarrow V$$
, where  $V = \{v_1, v_2, \dots, v_n\}$ 

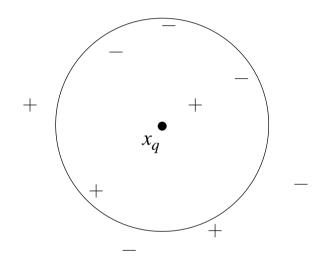
- Classification algorithm:
  - Given a query instance  $x_q$  to be classified
  - Let  $x_1, x_2, \ldots, x_k$  the k instances from training examples that are nearest to  $x_q$
  - Return

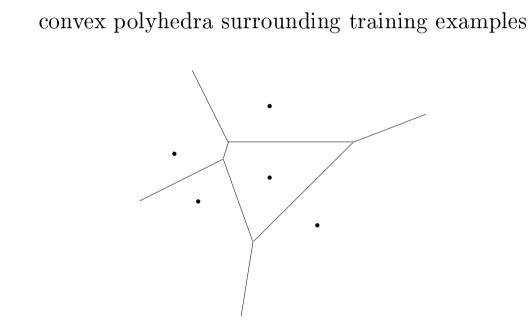
$$\hat{f}(x_q) \leftarrow \underset{v \in V}{\operatorname{argmax}} \sum_{i=1}^k \delta(v, f(x_i)) \tag{1}$$

where  $\delta(a, b) = 1$  if a = b and where  $\delta(a, b) = 0$  otherwise

- Approximation of real-valued target functions  $(f: \Re^n \longrightarrow \Re)$ 
  - Replace equation (1) in the classification algorithm by:

$$\hat{f}(x_q) \leftarrow \frac{\sum_{i=1}^k f(x_i)}{k} \tag{2}$$





5-nearest neighbor vs. 1-nearest neighbor

- Distance-weighted nearest neighbor algorithm
  - For discrete-valued target functions replace equation (1) by:

$$\hat{f}(x_q) \leftarrow \underset{v \in V}{argmax} \sum_{i=1}^k w_i \, \delta(v, f(x_i))$$

- For real-valued target functions replace equation (2) by:

$$\hat{f}(x_q) \leftarrow \frac{\sum_{i=1}^k w_i f(x_i)}{\sum_{i=1}^k w_i}$$

where 
$$w_i = \frac{1}{d(x_q, x_i)^2}$$

- Curse of dimensionality
  - Irrelevant attributes
  - Stretching the axes
  - (Leave-one-out) cross-validation

#### Locally Weighted Regression

• Explicit local approximation of the target function, usually by a linear function

$$\hat{f}(x) = w_0 + w_1 a_1(x) + \ldots + w_n a_n(x)$$

• Compute  $w_j$  in a way that the error for the query instance  $x_q$ 

$$E(x_q) = \frac{1}{2} \sum_{x \in k \text{ nearest nbrs of } x_q} (f(x) - \hat{f}(x))^2 K(d(x_q, x))$$

is minimized, where K(d) is the kernel function, usually equal to  $1/d^2$ 

• Computation of  $w_j$  may be done by gradient descent, giving:

$$\Delta w_j = \eta \sum_{x \in k \text{ nearest nbrs of } x_q} K(d(x_q, x)) \left(f(x) - \hat{f}(x)\right) a_j(x)$$

# Mάθηση κατά Bayes (Bayesian Learning)

- Naive Bayes classifier
- Each training example is described by a conjunction of attribute values  $\langle a_1, a_2, \ldots, a_n \rangle$ and the known target value (classification) of the example, from some finite set V
- Need to predict the target value of a new instance, given its attribute values
- Prediction is based on the Bayes theorem

$$P(v_j|a_1, a_2, \dots, a_n) = \frac{P(a_1, a_2, \dots, a_n | v_j) P(v_j)}{P(a_1, a_2, \dots, a_n)}$$

| Outlook  | Temperature           | Humidity                | Wind                    | PlayTennis |
|----------|-----------------------|-------------------------|-------------------------|------------|
| sunny    | $\operatorname{hot}$  | $\operatorname{high}$   | weak                    | no         |
| sunny    | $\operatorname{hot}$  | $\operatorname{high}$   | $\operatorname{strong}$ | no         |
| overcast | $\operatorname{hot}$  | $\operatorname{high}$   | weak                    | yes        |
| rain     | $\operatorname{mild}$ | $\operatorname{high}$   | weak                    | yes        |
| rain     | $\operatorname{cool}$ | $\operatorname{normal}$ | weak                    | yes        |
| rain     | $\operatorname{cool}$ | $\operatorname{normal}$ | $\operatorname{strong}$ | no         |
| overcast | $\operatorname{cool}$ | $\operatorname{normal}$ | $\operatorname{strong}$ | yes        |
| sunny    | $\operatorname{mild}$ | $\operatorname{high}$   | weak                    | no         |
| sunny    | $\operatorname{cool}$ | $\operatorname{normal}$ | weak                    | yes        |
| rain     | $\operatorname{mild}$ | $\operatorname{normal}$ | weak                    | yes        |
| sunny    | $\operatorname{mild}$ | $\operatorname{normal}$ | $\operatorname{strong}$ | yes        |
| overcast | $\operatorname{mild}$ | $\operatorname{high}$   | $\operatorname{strong}$ | yes        |
| overcast | $\operatorname{hot}$  | $\operatorname{normal}$ | weak                    | yes        |
| rain     | mild                  | $\operatorname{high}$   | $\operatorname{strong}$ | no         |

# A Playing Tennis Example

• The maximum a posteriori hypothesis  $v_{MAP}$  may be computed via the frequencies  $P(v_j)$  of target values and the frequencies of combinations of attribute values for specific target values  $P(a_1, a_2, \ldots, a_n | v_j)$ , in the training data

$$v_{MAP} = \operatorname{argmax}_{v_j \in V} P(v_j | a_1, a_2, \dots, a_n)$$
  
= 
$$\operatorname{argmax}_{v_j \in V} \frac{P(a_1, a_2, \dots, a_n | v_j) P(v_j)}{P(a_1, a_2, \dots, a_n)}$$
  
= 
$$\operatorname{argmax}_{v_j \in V} P(a_1, a_2, \dots, a_n | v_j) P(v_j)$$

• The naive Bayes classifier introduces the independence assumption

$$P(a_1, a_2, \dots, a_n | v_j) = \prod_i P(a_i | v_j)$$

for the reduction of the required probabilities, so

$$v_{MAP} \ (\equiv v_{NB}) = \underset{v_j \in V}{argmax} \ P(v_j) \prod_i P(a_i | v_j)$$

## Back to the Example

Will you play tennis when

Outlook=sunny, Temperature=cool, Humidity=high and Wind=strong?

$$v_{NB} = \underset{v_{j} \in \{yes, no\}}{\operatorname{argmax}} P(v_{j}) \prod_{i} P(a_{i}|v_{j})$$
$$= \underset{v_{j} \in \{yes, no\}}{\operatorname{argmax}} P(v_{j}) P(Outlook = sunny|v_{j}) P(Temperature = cool|v_{j})$$
$$P(Humidity = high|v_{j}) P(Wind = strong|v_{j})$$

$$P(yes) P(sunny|yes) P(cool|yes) P(high|yes) P(strong|yes) = \frac{9}{14} \frac{2}{9} \frac{3}{9} \frac{3}{9} \frac{3}{9} \frac{3}{9} = 0.0053$$

$$P(no) P(sunny|no) P(cool|no) P(high|no) P(strong|no) = \frac{5}{14} \frac{3}{5} \frac{1}{5} \frac{4}{5} \frac{3}{5} = 0.0206$$

Thus,  $v_{NB} = no$ 

• Introduction of m-estimate of probability to cope with probabilities equal to 0

$$\frac{n_c + mp}{n + m}$$

where, n is the number of examples with a specific target value,  $n_c$  the number of these examples with a specific attribute value, m is the *equivalent sample size* and p is the prior estimate of the probability we wish to determine (usually equal to 1/k, where k is the number of possible values of the attribute under consideration)

- Application to text classification (target values  $v_j$ )
  - Attributes are word positions  $a_i$  and values are words  $w_k$  from a vocabulary
  - Assumption: Values are independent from the positions,  $P(a_i = w_k | v_j) = P(w_k | v_j)$
  - Exploiting *m*-estimate of probability,  $P(w_k|v_j) = \frac{n_k+1}{n+|Vocabulary|}$
  - Using 2/3 of 20000 Usenet articles from 20 news groups as training data, classification of the rest 1/3 gave 89% accuracy, while random classification should give 5%